

On the Solvability of a Fourth-Order Initial Value Problem Under Barrier Strips Conditions

Todor Todorov, Petio Kelevedjiev

Abstract—This article is devoted to the existence of global solutions of the initial value problem for fourth-order nonlinear ordinary differential equation. To prove the established existence results we use a global existence theorem obtained in our previous work by a topological method, that is, the problem for the solvability of the considered initial value problem is replaced by the problem for the existence of a fixed point of a suitable introduced operator, the existence of a fixed point follows from the topological transversality theorem. The application of the global existence theorem needs a priori bounds which follow from imposed barrier strips conditions. In addition to an existence result, a result guaranteeing the existence of at least one positive, increasing (non-negative, non-decreasing), convex solution is also obtained.

Keywords—barrier strips, existence, fourth-order differential equations, initial value problem

I. INTRODUCTION

¹We study the existence of global solutions to the initial value problem (IVP)

$$x^{(4)} = f(t, x, x', x'', x'''), t \in [0, 1], \quad (1)$$

$$x(0) = A, x'(0) = B, x''(0) = C, x'''(0) = D, \quad (2)$$

where $A, B, C, D \in \mathbb{R}$, and $f(t, x, p, q, r)$ is a scalar function defined for $(t, x, p, q, r) \in [0, 1] \times D_x \times D_p \times D_q \times D_r$, here the sets $D_x, D_p, D_q, D_r \subseteq \mathbb{R}$ can be bounded.

The well-known Peano theorem guarantees a local solution to problem (1), (2) if $f(t, x, p, q, r)$ is continuous and bounded in a neighborhood of $(0, A, B, C, D)$, see for example P. Hartman [4].

The solvability of IVPs has been studied in W. Mydlarczyk [7] and N. Faried et al. [2]. The first article considers the problem

$$u'''(t) = g(u(t)), t > 0,$$

$$u(0) = u'(0) = u''(0) = 0,$$

where $g: (0, \infty) \rightarrow [0, \infty)$ is continuous. The second one is devoted to the fifth-order differential equation

$$\left(-\frac{d^2}{dt^2} + A^2\right)\left(\frac{d}{dt} + A\right)^3 u(t) + \sum_{j=1}^5 A_j \frac{d^{5-j}}{dt^{5-j}} u(t) = f(t),$$

$t \in \mathbb{R}$, with initial conditions

$$\frac{d^s u(0)}{dt^s} = 0, s = 0, 1, 2, 3,$$

where A is a self-adjoint positively defined operator and $A_j, j = 1, 2, 3, 4, 5$, are linear unbounded operators.

Numerical methods for fourth-order IVPs have been used in K. Hussain et al. [5], S. J. Kayode et al. [6] and I. Singh and G. Singh [8]; a Runge-Kutta type method, a block² method and the adomian decomposition method, respectively.

In our considerations we use a priori bounds. They are provided under the following assumptions.

(H₁) There are constants $F_i, L_i, i = 1, 2$, such that

$$F_2 < F_1 \leq D \leq L_1 < L_2, [F_2, L_2] \subseteq D_r,$$

$$f(t, x, p, q, r) \leq 0 \quad (3)$$

for $(t, x, p, q, r) \in [0, 1] \times D_x \times D_p \times D_q \times [L_1, L_2]$,

$$f(t, x, p, q, r) \geq 0 \quad (4)$$

for $(t, x, p, q, r) \in [0, 1] \times D_x \times D_p \times D_q \times [F_2, F_1]$.

(H₂) There are constants $-\infty < m_i, M_i < \infty, i = \overline{0, 3}$, such that

$$[m_0 - \sigma, M_0 + \sigma] \subseteq D_x, [m_1 - \sigma, M_1 + \sigma] \subseteq D_p,$$

$$[m_2 - \sigma, M_2 + \sigma] \subseteq D_q, [m_3 - \sigma, M_3 + \sigma] \subseteq D_r,$$

where $f(t, x, p, q, r)$ is continuous on the set $[0, 1] \times J$,

$$J = [m_0 - \sigma, M_0 + \sigma] \times [m_1 - \sigma, M_1 + \sigma] \times [m_2 - \sigma, M_2 + \sigma] \times [m_3 - \sigma, M_3 + \sigma],$$

and $\sigma > 0$ is a sufficiently small.

Let us recall that the strips $[0, 1] \times [L_1, L_2]$ and $[0, 1] \times [F_2, F_1]$ of (H₁) are called barrier ones, in this case for the third derivative of the eventual solutions $x \in C^4[0, 1]$ to a suitable family of boundary value problems (BVPs) containing IVP (1), (2).

We use the a priori bounds to apply the basic existence theorem given in R. Agarwal and P. Kelevedjiev [1]. In fact, it is a variant of A. Granas et al. [3], Chapter I, Theorem 5.1 and Chapter V, Theorem 1.2. To formulate this theorem we consider the BVP

$$x^{(4)} + a(t)x''' + b(t)x'' + c(t)x' + d(t)x = f(t, x, x', x'', x'''), t \in [0, 1], \quad (5)$$

$$V_i(x) = r_i, i = 1, 2, 3, 4, \quad (6)$$

where $a, b, c, d \in C([0, 1], \mathbb{R})$, $f: [0, 1] \times D_x \times D_p \times D_q \times D_r \rightarrow \mathbb{R}$,

$$V_i(x) = \sum_{j=0}^2 [a_{ij}x_0^{(j)} + b_{ij}x_1^{(j)}], i = \overline{1, 4},$$

Received: 18.09.2024

Published: 30.09.2024

<https://doi.org/10.47978/TUS.2024.74.03.011>

Todor Todorov is with the Technical University of Sofia (evgeniya.vasileva@tu-sofia.bg)

Peter Kelevedjiev is with the Technical University of Sofia (pskeleved@abv.bg)

with $\sum_{j=0}^2(a_{ij}^2 + b_{ij}^2) > 0, i = \overline{1,4}$, and $r_i \in \mathbb{R}, i = \overline{1,4}$.

Introduce also the following family of BVPs

$$\begin{aligned} x^{(4)} + a(t)x''' + b(t)x'' + c(t)x' + d(t)x &= \\ = g(t, x, x', x'', x''', \lambda), t \in [0,1], \end{aligned} \quad (5)_\lambda$$

with boundary conditions (6), where $\lambda \in [0,1]$, the function g is defined on $[0,1] \times D_x \times D_p \times D_q \times D_r \times [0,1]$, and a, b, c, d are as above.

Let BC denote the set of functions satisfying (6), and BC_0 denote the set of functions satisfying the homogenous BCs (6), that is,

$$V_i(x) = 0, i = \overline{1,4}.$$

Finally, let $C_{BC}^4[0,1] = C^4[0,1] \cap BC$ and $C_{BC_0}^4[0,1] = C^4[0,1] \cap BC_0$.

Now we are ready to formulate our basic tool.

Theorem 1.1. [Theorem 4, [1]]. *Assume that:*

- (i) *Problem (5)₀, (6) has a unique solution $x_0 \in C^4[0,1]$.*
- (ii) *Problems (5), (6) and (5)₁, (6) are equivalent.*
- (iii) *The map $L_h: C_{BC_0}^4 \rightarrow C[0,1]$, defined by*

$$L_h x = x^{(4)} + a(t)x''' + b(t)x'' + c(t)x' + d(t)x,$$

is one-to-one.

- (iv) *Each solution $x \in C^4[0,1]$ to family (5)_λ, (6) satisfies the bounds*

$$m_i \leq x^{(i)}(t) \leq M_i \text{ for } t \in [0,1], i = \overline{0,4},$$

where the constants $-\infty < m_i, M_i < \infty, i = \overline{1,4}$ are independent of λ and x .

- (v) *There is a sufficiently small $\sigma > 0$, such that*

$$[m_0 - \sigma, M_0 + \sigma] \subseteq D_x, [m_1 - \sigma, M_1 + \sigma] \subseteq D_p,$$

$$[m_2 - \sigma, M_2 + \sigma] \subseteq D_q, [m_3 - \sigma, M_3 + \sigma] \subseteq D_r,$$

and the function $g(t, x, p, q, r, \lambda)$ is continuous for $(t, x, p, q, r, \lambda) \in [0,1] \times J \times [0,1]$,

where

$$\begin{aligned} J = [m_0 - \sigma, M_0 + \sigma] \times [m_1 - \sigma, M_1 + \sigma] \times \\ \times [m_2 - \sigma, M_2 + \sigma] \times [m_3 - \sigma, M_3 + \sigma], \end{aligned}$$

and $m_i, M_i, i = \overline{0,3}$ are as in (iv).

Then boundary value problem (5), (6) has at least one solution in $C^4[0,1]$.

In this paper the equation (5)_λ has the form

$$x^{(4)} = \lambda f(t, x, x', x'', x'''), t \in [0,1]. \quad (1)_\lambda$$

In fact, we apply Theorem 1.1 on the family of BVPs (1)_λ, (2), which is of the form (5)_λ, (6), and on the IVP (1), (2), which is of the form (5), (6).

II. A PRIORI BOUNDS

In this part we state results, which assure the a priori bounds from (iv) for the eventual $C^4[0,1]$ -solutions to the family IVPs (1)_λ, (2).

Lemma 2.1. *Let $x \in C^4[0,1]$ be a solution to (1)_λ, (2) and (H₁) hold. Then*

$$F_1 \leq x'''(t) \leq L_1 \text{ for } t \in [0,1].$$

Proof. Suppose that there is a $t \in [0,1]$ for which $x'''(t) > L_1$. Then, from the continuity of $x'''(t)$ on the interval $[0,1]$ and from $x'''(0) \leq L_1$ it follows that the set

$$S_- = \{t \in [0,1]: L_1 < x'''(t) \leq L_2\}$$

is not empty and there is a $\varphi \in S_-$ such that $x^{(4)}(\varphi) > 0$. Since $x(t)$ is a $C^4[0,1]$ -solution to differential equation (1)_λ, we have in particular

$$x^{(4)}(\varphi) = \lambda f(\varphi, x(\varphi), x'(\varphi), x''(\varphi), x'''(\varphi)).$$

But,

$$(\varphi, x(\varphi), x'(\varphi), x''(\varphi), x'''(\varphi)) \in S_- \times \mathbb{R}^3 \times (L_1, L_2].$$

This means that we can use (3) to conclude that $x^{(4)}(\varphi) \leq 0$. The obtained contradiction shows that

$$x'''(t) \leq L_1 \text{ for } t \in [0,1].$$

Similarly, using (4), we establish

$$F_1 \leq x'''(t) \text{ for } t \in [0,1].$$

Lemma 2.2. *Let $x \in C^4[0,1]$ be a solution to (1)_λ, (2) and (H₁) hold. Then*

$$|x(t)| \leq |A| + |B| + |C| + \max\{|F_1|, |L_1|\}, t \in [0,1],$$

$$|x'(t)| \leq |B| + |C| + \max\{|F_1|, |L_1|\}, t \in [0,1],$$

$$|x''(t)| \leq |C| + \max\{|F_1|, |L_1|\}, t \in [0,1].$$

Proof. By the mean value theorem, for each $t \in (0,1]$ there exists an $\eta \in (0, t)$ such that

$$x''(t) - x''(0) = x'''(\eta)(t - 0), t \in (0,1],$$

$$|x''(t)| \leq |x''(0)| + |x'''(\eta)||t|, t \in (0,1],$$

$$|x''(t)| \leq |C| + |x'''(\eta)|, t \in [0,1].$$

But from Lemma 2.1 we know that

$$F_1 \leq x'''(t) \leq L_1, t \in [0,1],$$

that is,

$$|x'''(t)| \leq \max\{|F_1|, |L_1|\}, t \in [0,1],$$

and in particular

$$|x'''(\eta)| \leq \max\{|F_1|, |L_1|\}.$$

Thus,

$$|x''(t)| \leq |C| + \max\{|F_1|, |L_1|\}, t \in [0,1].$$

To prove the bound for $|x'(t)|$, we use again the mean value theorem. Now, for each $t \in (0,1]$ there is a $\zeta \in (0, t)$ such that

$$x'(t) - x'(0) = x''(\zeta)(t - 0), t \in (0,1],$$

$$|x'(t)| \leq |x'(0)| + |x''(\zeta)||t|, t \in (0,1],$$

$$|x'(t)| \leq |B| + |x''(\zeta)|, t \in [0,1],$$

$$|x'(t)| \leq |B| + |C| + \max\{|F_1|, |L_1|\}, t \in [0,1].$$

Finally, we apply the Lagrange theorem on $x(t)$. For each $t \in (0,1]$ there is a $v \in (0, t)$ for which

$$x(t) - x(0) = x'(v)(t - 0), t \in (0,1],$$

$$|x(t)| \leq |x(0)| + |x'(v)||t|, t \in (0,1],$$

$$|x(t)| \leq |A| + |x'(v)|, t \in [0,1],$$

$$|x(t)| \leq |A| + |B| + |C| + \max\{|F_1|, |L_1|\}, t \in [0,1].$$

Lemma 2.3. *Let (H₁) holds and (H₂) holds for*

$$M_0 = |A| + |B| + |C| + \max\{|F_1|, |L_1|\}, m_0 = -M_0,$$

$$M_1 = |B| + |C| + \max\{|F_1|, |L_1|\}, m_1 = -M_1,$$

$$M_2 = |C| + \max\{|F_1|, |L_1|\}, m_2 = -M_2,$$

$$M_3 = L_1, m_3 = F_1.$$

Then there are constants m_4 and M_4 such that $m_4 \leq x^{(4)}(t) \leq M_4, t \in [0,1]$.

Proof. Because of the continuity of $f(t, x, p, q, r)$ on the set $[0,1] \times J$, there exist constants m_4 and M_4 such that

$$m_4 \leq f(t, x, p, q, r) \leq M_4 \text{ for } (t, x, p, q, r) \in [0,1] \times J.$$

Since from Lemmas 2.1 and 2.2 we have $(x(t), x'(t), x''(t), x'''(t)) \in J$ for $t \in [0,1]$, equation (1)_λ implies

$$m_4 \leq x^{(4)}(t) \leq M_4 \text{ for } t \in [0,1].$$

Corollary 2.4. Let $A, B, C, D \geq 0$ and **(H₁)** hold with $F_1 \geq 0$. Then each solution $x(t) \in C^4[0,1]$ to (1)_λ, (2) satisfies the bounds

$$A \leq x(t) \leq A + B + C + L_1, t \in [0,1],$$

$$B \leq x'(t) \leq B + C + L_1, t \in [0,1],$$

$$C \leq x''(t) \leq C + L_1, t \in [0,1].$$

Proof. By Lemma 2.1 we have $x'''(t) \geq F_1 \geq 0, t \in [0,1]$, which means that $x''(t)$ is non-decreasing on $[0,1]$ and so

$$x''(t) \geq C, t \in [0,1].$$

Besides, by applying Lemma 2.2, we get

$$x''(t) \leq C + L_1, t \in [0,1].$$

Next, using $x''(t) \geq C \geq 0$ for $t \in [0,1]$ and Lemma 2.2, we establish

$$B \leq x'(t) \leq B + C + L_1, t \in [0,1].$$

The bound for $x(t)$ follows similarly.

III. EXISTENCE RESULTS

Theorem 3.1. Let **(H₁)** holds. Let in addition **(H₂)** holds for

$$M_0 = |A| + |B| + |C| + \max\{|F_1|, |L_1|\}, m_0 = -M_0,$$

$$M_1 = |B| + |C| + \max\{|F_1|, |L_1|\}, m_1 = -M_1,$$

$$M_2 = |C| + \max\{|F_1|, |L_1|\}, m_2 = -M_2,$$

$$M_3 = L_1, m_3 = F_1.$$

Then IVP (1),(2) has at least one solution in $C^4[0,1]$.

Proof. We will show that the family of BVPs (1)_λ, (2) and the IVP (1), (2) satisfy all hypotheses of Theorem 3.1. By standard reasoning check that (i) is fulfilled, see the proof of Theorem 2.5 of T. Todorov [9]. Apparently (ii) also holds. To check (iii) we establish, by standard reasoning, that for an arbitrary $y(t) \in C[0, 1]$ the IVP

$$x^{(4)} = y(t),$$

$$x(0) = 0, x'(0) = 0, x''(0) = 0, x'''(0) = 0,$$

has a unique solution in $C^4[0,1]$, that is, the map $\Lambda_h: C_{BC_0}^4[0,1] \rightarrow C[0,1]$, defined by $\Lambda_h x = x^{(4)}$, is one-to-one. Hence, (iii) holds. Furthermore, for each solution $x(t) \in C^4[0,1]$ to (1)_λ, (2) we have

$$m_i \leq x^{(i)}(t) \leq M_i, t \in [0,1], i = \overline{0,4}, \text{ by Lemma 2.3.}$$

Therefore, (iv) also holds. Finally, (v) follows from the continuity of f on the set J . Thus, we can apply Theorem 3.1 to conclude that the assertion is true.

Under a suitable combination of the signs of A, B, C and D , **(H₁)** guarantees solutions with important properties.

Theorem 3.2. Let $A, B > 0 (A = B = 0), C \geq 0, D \geq 0$. Suppose **(H₁)** holds with $F_1 \geq 0$ and **(H₂)** holds for

$$m_0 = A, M_0 = A + B + C + L_1, m_1 = B + C,$$

$$M_1 = B + C + L_1,$$

$$m_2 = C, M_2 = C + L_1, m_3 = F_1, M_3 = L_1.$$

Then IVP (1), (2) has at least one positive, increasing (non-negative, non-decreasing), convex solution in $C^4[0,1]$.

Proof. Following the proof of Theorem 3.1, we establish that there is a solution $x(t) \in C^4[0,1]$. Now, the bounds $m_i \leq x^{(i)}(t) \leq M_i, t \in [0,1], i = 0, 1, 2$, follow from Corollary 2.4. Actually Corollary 2.4 implies in particular

$$x(t) \geq A > 0, x'(t) \geq B > 0 \quad (x(t) \geq 0, x'(t) \geq 0),$$

$$x''(t) \geq C \geq 0 \text{ for } t \in [0,1],$$

which yields the assertion.

IV. AN EXAMPLE

Consider the initial value problem

$$x^{(4)} = P_n(x'''), t \in [0,1],$$

$$x(0) = A, x'(0) = B, x''(0) = C, x'''(0) = D,$$

where the polynomial $P_n(r), n \geq 2$, has simple zeros z_1 and z_2 such that $z_1 < D < z_2$.

Obviously, there is a $\theta > 0$ such that

$$z_1 + \theta \leq D \leq z_2 - \theta$$

and

$$P_n(p) \neq 0 \text{ for } r \in \bigcup_{i=1}^2 ((z_i - \theta, z_i + \theta) \setminus \{z_i\}).$$

Let $P_n(r) > 0$ for

$$r \in (z_1 - \theta, z_1) \text{ and } P_n(r) < 0 \text{ for } p \in (z_2, z_2 + \theta);$$

analogously we can consider the other cases. Then **(H₁)** holds for $F_2 = z_1 - \theta, F_1 = z_1, L_1 = z_2, L_2 = z_2 + \theta$. Since $P_n(r)$ is continuous, **(H₂)** also holds. So, we can apply Theorem 3.1 which means the considered problem has at least one solution in $C^4[0,1]$.

REFERENCES

- [1] R. P. Agarwal, P. S. Kelevedjiev, "On the solvability of fourth-order two-point boundary value problems", *Mathematics*, 8 (4), 603, 2020, doi: 10.3390/math8040603.
- [2] N. Faried, L. Rashed, A. I. Ahmed, M. A. Labeeb, "Solvability of initial-boundary value problem of a multiple characteristic fifth-order operator-differential equation", *J. Egypt. Math. Soc.*, 27, Article 37, 2019, doi: 10.1186/s42787-019-0036-7.
- [3] A. Granas, R. B. Guenther, J. W. Lee, *Nonlinear Boundary Value Problems for Ordinary Differential Equations*, Dissnes Math., Warszawa, 1985, Identifikator YADDA: bwmeta1.element.zamlynska-d191e607-1373-43f5-abad-b660628c2a50.
- [4] P. Hartman, *Ordinary Differential Equations*, John Wiley & Sons, New-York-London-Sydney, 1964.
- [5] K. Hussain, F. Ismail, N. Senu, "Solving directly special fourth-order ordinary differential equations using Runge–Kutta type method", *J. Comput. Appl. Math.*, doi: 10.1016/j.cam.2016.04.002.
- [6] S. J. Kayode, M. Duromola, B. Bolaji, "Direct solution of initial value problems of fourth order ordinary differential equations using modified implicit hybrid block method", *Journal of Scientific Research and Reports*, 3(21), 2792-2800, 2014, doi: 10.9734/JSRR/2014/11953.

- [7] M. Mydlarczyk, "An initial value problem for a third order differential equation", *Annales Polonici Mathematici*, Lix. 3, 215-223, [https:// bibliotekanauki.pl/articles/1311663.pdf](https://bibliotekanauki.pl/articles/1311663.pdf).
- [8] I. Singh, G. Singh, "Numerical study for solving fourth order ordinary differential equations", *International Journal for Research in Engineering Application & Management (IJREAM)*, 5(1), 638-642, 2019, doi: 10.18231/2454-9150.2019.0371.
- [9] T. Todorov, "Existence of solutions of a two-point fourth-order boundary value problem under barrier strips conditions", *Announcements of the Union of Scientists-Sliven*, 38(2), 95-99, 2023.